

ABSTRACT

A joint of an industrial robot that includes attaching part (23) having positioning member (22) embedded in one or both of two relatively rotating members, and guide (24) through which positioning member (22) projectably slides. Meanwhile, the side of the positioning member is provided thereon with a reservoir groove for a lubricant and a projection position marker for indicating a given projection length. This makeup provides an inexpensive, highly accurate, and extremely trouble-saving origin adjusting device.